

Absolute encoders – multiturn

Standard electronic multiturn, magnetic	Sendix M5868 (shaft)	SAE J1939
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Technical data

Mechanical characteristics	
Maximum speed	4000 min ⁻¹ 2000 min ⁻¹ (continuous)
Starting torque at 20°C [68°F]	< 0.01 Nm
Shaft load capacity	radial 80 N axial 40 N
Weight	approx. 0.2 kg [7.06 oz]
Protection acc. to EN 60529/DIN 40050-9	IP65
Working temperature range	-40°C ... +85°C [-40°F ... +185°F]
Materials	shaft V2A flange aluminum housing zinc die-cast cable PVC
Shock resistance acc. to EN 60068-2-27	5000 m/s ² , 4 ms
Vibration resistance acc. to EN 60068-2-6	300 m/s ² , 10 ... 2000 Hz
Electrical characteristics	
Power supply	10 ... 30 V DC
Current consumption (no load)	max. 30 mA
Reverse polarity protection of the power supply	yes
Short-circuit proof outputs	yes ¹⁾
CE compliant acc. to	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU

Interface characteristics SAE J1939	
Resolution singleturn	1 ... 16.384 (14 bit), scalable default: 16.384 (14 bit)
Absolute accuracy ²⁾	±1°
Repeat accuracy	±0.2°
Number of revolutions (multiturn)	max. 536.870.912 (29 bit) scalable only via the total resolution default: 262.144 (18 bit)
Total resolution	1 ... 8.796.093.022.208 (43 bit), scalable default: 4.294.967.296 (32 bit)
Interface	CAN high-speed acc. to ISO 11898, CAN specification 2.0 B
Protocol	SAE J1939
Power-ON time	< 1200 ms
Baud rate	250 kbit/s switchable by software to 500 kbit/s
Node address	software configurable
Termination	software configurable

1) Short circuit proof to 0 V or to output when power supply correctly applied.

2) Over the whole temperature range.

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General information concerning SAE J1939

The protocol J1939 originates from the international Society of Automotive Engineers (SAE) and operates on the physical layer with high speed CAN as per ISO11898. The application emphasis lies in the area of the power train and chassis of commercial vehicles. It serves to transfer diagnostic data (for example, motor speed, position, temperature) and control information. Type series M3658 and M3678 encoders support the total functionality of J1939.

This protocol is a multimaster system with decentralized network management that does not involve channel-based communication.

It supports up to 254 logic nodes and 30 physical control devices per segment. The information is described as parameters (signals) and combined on 4 memory pages (data pages) into parameter groups (PGs). Each parameter group can be identified via a unique number, the parameter group number (PGN). Independently of this, each signal is assigned a unique SPN (suspect parameter number).

The major part of the communication occurs cyclically and can be received by all control devices without the explicit request for data (Broadcast). Furthermore the parameter groups are optimized to a length of 8 data bytes. This enables very efficient utilization of the CAN protocol. If greater amounts of data need to be transferred, then transport protocols (TP) can be used: BAM (broadcast announce message) and CMDT (connection mode data transfer). With BAM TP the transfer of data occurs as a broadcast.

Encoder implementation SAE J1939

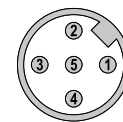
- PGNs that are adaptable to the customer's application.
- Resolution of address conflicts -> Address Claiming (ACL).
- Continuous checking whether control addresses have been assigned twice within a network.
- Change of control device addresses during run-time.
- Unique identification of a control device with the help of a name that is unique worldwide. This name serves to identify the functionality of a control device in the network.
- Predefined PGs for position, speed and alarm.
- 250 kbit/s, 29 bit identifier.
- Watchdog controlled device.

A two-color LED, located on the rear of the encoder, signals the operating and fault status of the J1939 protocol, as well as the status of the internal sensor diagnostics.

Terminal assignment

Interface	Type of connection	Cable (isolate unused wires individually before initial start-up)					
2	2, B	Signal:	+V	0 V	CAN_GND	CAN_H	CAN_L
		Cable color:	BN	WH	GY	GN	YE
Interface	Type of connection	M12 connector, 5-pin					
2	4	Signal:	+V	0 V	CAN_GND	CAN_H	CAN_L
		Pin:	2	3	1	4	5

Top view of mating side, male contact base



M12 connector, 5-pin

