

# Absolute encoders – multiturn

**Compact, robust  
electronic multiturn, magnetic**

**Sendix M3668R (shaft)**

**SAE J1939**

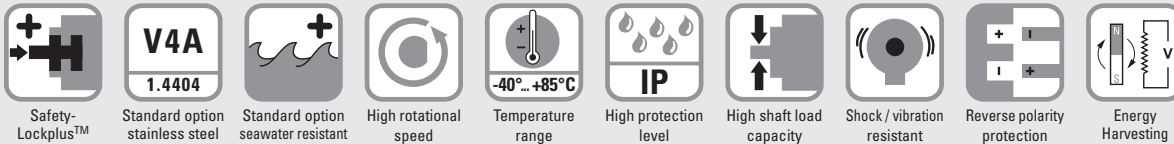


The Sendix M36 with Energy Harvesting Technology is an electronic multiturn encoder in miniature format, without gear and without battery. It is characterized by robustness, reliability and cost-efficiency.

The "R"obust version is particularly suitable for use in harsh environments. Protected up to IP69k, resistance against shock and extreme temperature fluctuations, the Sendix M36 encoder is suitable even for demanding outdoor applications.



**SAE J1939**



## Highest robustness

- Sturdy bearing construction in Safety-Lockplus™ design for particularly high resistance.
- Extra large bearings.
- Mechanically protected shaft seal.
- Protection level IP66, IP67 and IP69k in one device.
- Wide temperature range -40°C ... +85°C.
- Without gear and without battery, thanks to the Energy Harvesting technology.

## Up-to-the-minute fieldbus performance

- Up-to-the-minute fieldbus performance in the application: SAE J1939 with CAN-highspeed to ISO 11898.
- Universal Scaling Function.
- Fast determination of the operating status via two-color LED.

**Order code** 8.M3668R.XX3X.3222  
**Shaft version** Type

- a** Version  
1 = standard <sup>1)</sup>  
clamping flange  $\varnothing$  42 mm [1.65"]  
7 = stainless steel V4A <sup>2)</sup>  
clamping flange  $\varnothing$  42 mm [1.65"]  
all metal parts accessible from outside  
are out of stainless steel V4A

- b** Shaft ( $\varnothing \times L$ ), with flat  
1 =  $\varnothing$  6 x 12.5 mm [0.24 x 0.49"]  
3 =  $\varnothing$  8 x 15 mm [0.32 x 0.59"]  
5 =  $\varnothing$  10 x 20 mm [0.39 x 0.79"]  
2 =  $\varnothing$  1/4" x 12.5 mm [0.49"]  
E =  $\varnothing$  10 x 20 mm [0.39 x 0.79"],  
stainless steel V4A

- c** Interface / power supply  
3 = SAE J1939 / 10 ... 30 V DC

- d** Type of connection  
2 = radial cable, 1 m [3.28'] PVC  
B = radial cable, special length PVC \*)  
4 = radial M12 connector, 5-pin

- \*) Available special lengths (connection type B):  
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.M3668.133B.3222.0030 (for cable length 3 m)

- e** Fieldbus profile  
32 = SAE J1939

- Optional on request*  
- Ex 2/22 (only for connection type 4)  
- other shaft diameters out of V4A  
stainless steel

1) Not in conjunction with shaft type "E".  
2) Only in conjunction with shaft type "E" + type of connection "4".

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<b>Compact, robust electronic multiturn, magnetic</b>	<b>Sendix M3668R (shaft)</b>	<b>SAE J1939</b>
<b>Mounting accessory for shaft encoders</b>		Order no.
<b>Coupling</b>	Bellows coupling ø 19 mm [0.75"] for shaft 8 mm [0.32"]	<b>8.0000.1102.0808</b> <sup>1)</sup>
<b>Connection technology</b>		Order no.
<b>Cordset, pre-assembled</b>	M12 female connector with coupling nut, 5-pin 5 m [19.69"] PVC cable	<b>05.00.6091.A211.005M</b> <sup>1)</sup>
<b>Connector, self-assembly (straight)</b>	M12 female connector with coupling nut, 5-pin	<b>8.0000.5116.0000</b> <sup>1)</sup>

Further accessories can be found in the accessories section or in the accessories area of our website at: [www.kuebler.com/accessories](http://www.kuebler.com/accessories).  
Additional connectors can be found in the connection technology section or in the connection technology area of our website at: [www.kuebler.com/connection\\_technology](http://www.kuebler.com/connection_technology).

## Technical data

Mechanical characteristics			Interface characteristics SAE J1939		
<b>Maximum speed</b>	4000 min <sup>-1</sup> 2000 min <sup>-1</sup> (continuous)		<b>Resolution singleturn</b>	1 ... 16.384 (14 bit), scalable default: 16.384 (14 bit)	
<b>Starting torque at 20°C [68°F]</b>	< 0.01 Nm		<b>Absolute accuracy</b> <sup>3)</sup>	±1°	
<b>Shaft load capacity</b>	radial	80 N	<b>Repeat accuracy</b>	±0.2°	
	axial	40 N	<b>Number of revolutions (multiturn)</b>	max. 536.870.912 (29 bit) scalable only via the total resolution default: 262.144 (18 bit)	
<b>Weight</b>	approx. 0.2 kg [7.06 oz]		<b>Total resolution</b>	1 ... 8.796.093.022.208 (43 bit), scalable default: 4.294.967.296 (32 bit)	
<b>Protection acc. to EN 60529/DIN 40050-9</b>	IP66, IP67, IP69k		<b>Interface</b>	CAN high-speed acc. to ISO 11898, CAN specification 2.0 B	
<b>Working temperature range</b>	-40°C ... +85°C [-40°F ... +185°F]		<b>Protocol</b>	SAE J1939	
<b>Materials</b>	<b>version "1"</b> (standard)	<b>version "7"</b> (stainless steel)	<b>Power-ON time</b>	< 1200 ms	
	shaft	V2A	V4A	<b>Baud rate</b>	250 kbit/s switchable by software to 500 kbit/s
	flange	aluminum	V4A	<b>Node address</b>	software configurable
	housing	zinc die-cast	V4A	<b>Termination</b>	software configurable
	cable	PVC	–		
<b>Shock resistance acc. to EN 60068-2-27</b>	5000 m/s <sup>2</sup> , 4 ms				
<b>Vibration resistance acc. to EN 60068-2-6</b>	300 m/s <sup>2</sup> , 10 ... 2000 Hz				
Electrical characteristics					
<b>Power supply</b>	10 ... 30 V DC				
<b>Current consumption (no load)</b>	max. 30 mA				
<b>Reverse polarity protection of the power supply</b>	yes				
<b>Short-circuit proof outputs</b>	yes <sup>2)</sup>				
<b>e1 compliant acc. to (pending)</b>	EU guideline 2009/19/EC (acc. to EN 55025, ISO 11452 and ISO 7637)				
<b>UL approval</b>	File no. E224618				
<b>CE compliant acc. to</b>	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU				

1) Not for version "7" (V4A stainless steel)  
2) Short circuit proof to 0 V or to output when power supply correctly applied.  
3) Over the whole temperature range.

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**SAE J1939**

## General information concerning SAE J1939

The protocol J1939 originates from the international Society of Automotive Engineers (SAE) and operates on the physical layer with high speed CAN as per ISO11898. The application emphasis lies in the area of the power train and chassis of commercial vehicles. It serves to transfer diagnostic data (for example, motor speed, position, temperature) and control information. Type series M3658 and M3678 encoders support the total functionality of J1939.

This protocol is a multimaster system with decentralized network management that does not involve channel-based communication.

It supports up to 254 logic nodes and 30 physical control devices per segment. The information is described as parameters (signals) and combined on 4 memory pages (data pages) into parameter groups (PGs). Each parameter group can be identified via a unique number, the parameter group number (PGN). Independently of this, each signal is assigned a unique SPN (suspect parameter number).

The major part of the communication occurs cyclically and can be received by all control devices without the explicit request for data (Broadcast). Furthermore the parameter groups are optimized to a length of 8 data bytes. This enables very efficient utilization of the CAN protocol. If greater amounts of data need to be transferred, then transport protocols (TP) can be used: BAM (broadcast announce message) and CMDT (connection mode data transfer). With BAM TP the transfer of data occurs as a broadcast.

## Encoder implementation SAE J1939

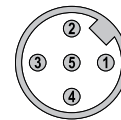
- PGNs that are adaptable to the customer's application.
- Resolution of address conflicts -> Address Claiming (ACL).
- Continuous checking whether control addresses have been assigned twice within a network.
- Change of control device addresses during run-time.
- Unique identification of a control device with the help of a name that is unique worldwide. This name serves to identify the functionality of a control device in the network.
- Predefined PGs for position, speed and alarm.
- 250 kbit/s, 29 bit identifier.
- Watchdog controlled device.

A two-color LED, located on the rear of the encoder, signals the operating and fault status of the J1939 protocol, as well as the status of the internal sensor diagnostics.

## Terminal assignment

Interface	Type of connection	Cable (isolate unused cores individually before initial start-up)					
2	2, B	Signal:	+V	0 V	CAN_GND	CAN_H	CAN_L
		Core color:	BN	WH	GY	GN	YE
Interface	Type of connection	M12 connector, 5-pin					
2	4	Signal:	+V	0 V	CAN_GND	CAN_H	CAN_L
		Pin:	2	3	1	4	5

Top view of mating side, male contact base



M12 connector, 5-pin

1) Over the whole temperature range.

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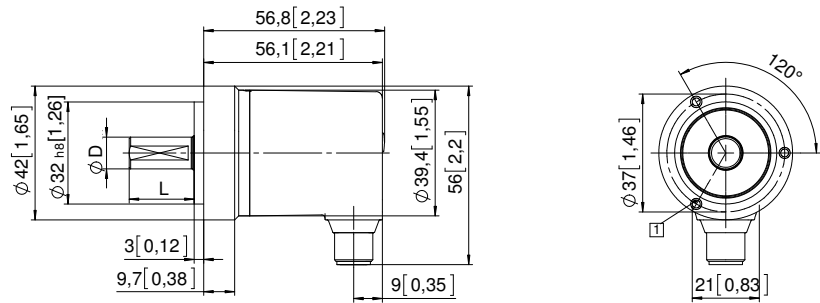
## Dimensions

Dimensions in mm [inch]

**Aluminum,**  
clamping flange,  $\varnothing$  42 [1.65]  
version 1

1 3 x M3, 6 [0.24] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]



**Stainless steel V4A**  
clamping flange,  $\varnothing$  42 [1.65]  
version 7

1 4 x M4, 8 [0.31] deep

D	Fit	L
6 [0.24]	h7	12.5 [0.49]
8 [0.32]	h7	15 [0.59]
10 [0.39]	f7	20 [0.79]
1/4"	h7	12.5 [0.49]

